

## NEW YORK CITY CONNECTED VEHICLE PILOT PROJECT

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New York City is aggressively pursuing "Vision Zero" "Traffic Death and Injury on City streets is not acceptable" Vision Zero Goal : to eliminate traffic deaths by 2024

#### NYC CV Pilot will evaluate

- Safety benefits of CV technology
- Address CV deployment challenges
  - With a Large number of vehicles & types
  - Issues associated with the dense urban environment







## LOCATIONS (MANHATTAN, BROOKLYN)





## **CV STAKEHOLDER/USER DEPLOYMENT**

#### **Vehicles**

- Up to 8,000 fleet vehicles with Aftermarket Safety Devices (ASDs):
  - ~5,800 Taxis (Yellow Cabs)
  - ~ 700 MTA Buses
  - 1,050 Sanitation & DOT vehicles
  - ~ 400 DCAS vehicles

#### **Revenue Vehicles**

#### **Pedestrians**

- Pedestrian PIDs
  - Visually Impaired
  - 100 Subjects PID
- PED in Crosswalk
  - 10 Fully Instrumented Int.



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#### **Operating Statistics:**

Vehicles are in motion or active ~**14 hours per day!** Average taxi drives 197 miles per day Fleet total Vehicle Miles Traveled: >**1.3 Million Miles per day** ~**40 Million Miles per month** 



# SAFETY APPLICATIONS

#### Vehicle-to-Vehicle (V2V) Safety Applications

- Vehicle Turning Right in Front of Bus Warning
- Forward Collision Warning
- Emergency Electronic Brake Light
- Blind Spot Warning
- Lane Change Warning/Assist
- Intersection Movement Assist

#### Vehicle-to-Infrastructure (V2I) Safety Applications

- Red Light Violation Warning
- Speed Compliance
- Curve Speed Compliance
- Speed Compliance/Work Zone
- Oversize Vehicle Compliance
  - Prohibited Facilities (Parkways)
  - Over Height
- Emergency Communications and Evacuation Information (Traveler Information)







## **ADDITIONAL APPLICATIONS**

#### **Pedestrian**

- Mobile [Visually Impaired] Ped Signal System navigation assistance
- Pedestrian in Signalized Intersection Warning to vehicles

#### Traffic Management

CV Data for Intelligent Traffic Signal System

Roadway segment travel times

#### **Operations, Maintenance, and Performance Analysis**

- RF Monitoring
- OTA Firmware Update
- Parameter Up/Down Loading
- Traffic data collection
- Event History Recording
- Event History Up Load

To Evaluate the benefits

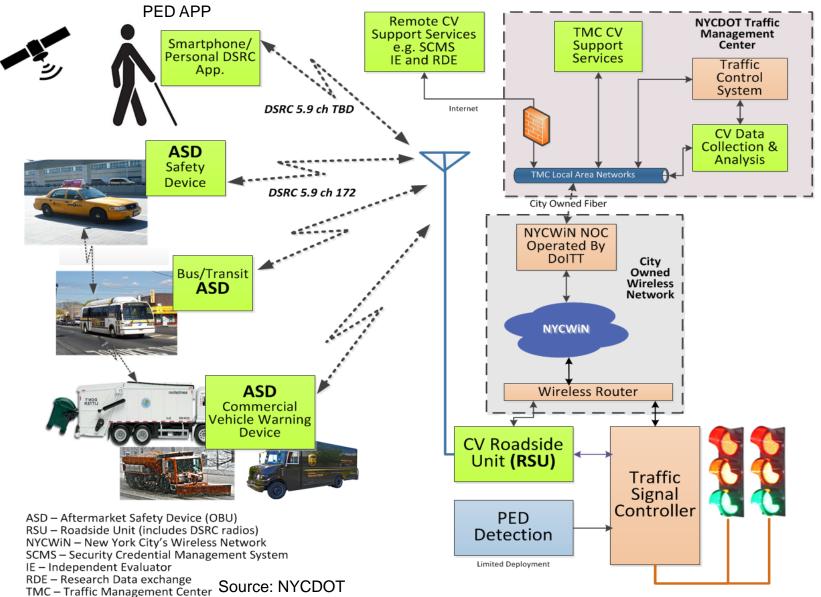






## OVERALL PROJECT CONCEPT





NYC Connected Vehicle Project



# Where are we now ?



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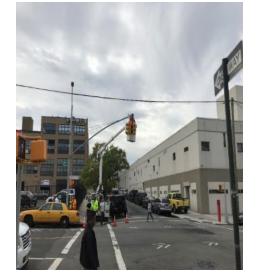


## **PROTOTYPE INSTALLATION AND TESTING**

- Developing MAP message Content (USDOT tool)
- RSU Planning installation sites
  - Establishing Installation "partners"
  - Optimizing for triangulation and location accuracy testing
- ASD Developing vehicle installation kit designs
  - Working with vendors NY Specific Software
  - Working with Fleet owners Establish installation procedures
  - Running samples awaiting prototypes checking coverage and interference



VYC Connected Vehicle Project For Safer Transportation





~360 Roadside Units 36 Units at key locations

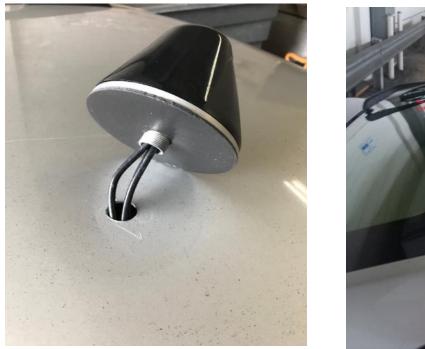






#### **VEHICLE INSTALLATION**









- 80 Samples installed in fleet vehicle
- Testing through the glass and drilled mountings
- Working with various different vehicle types
- Verifying calibration and RF radiation patterns





## NYC DOT INSTALLATIONS



- NYC DOT Installation
  - Various Makes/Models/Year NYC DOT vehicles are being equipped with prototype ASDs in order to fine tune and optimize installation methods and approaches
  - NYC DOT Vehicles 770
    - Toyota
      - Prius, RAV4
    - Ford
      - Fusion
      - F-150 F-550
    - Chevrolet
      - Silverado
      - HD3500
      - Economy







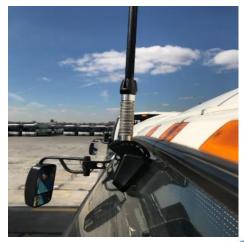
## MTA INSTALLATION

- The buses were installed to test RF DSRC communication with light vehicles, and to develop an installation template
- Key element for MTA Through the glass Antenna







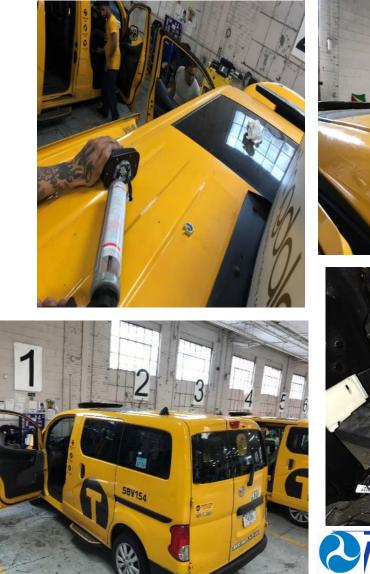






## **TAXI INSTALLATION**

- Taxi Installations are estimated at 5000 vehicles between the participating fleet owners
- 2 authorized technology installers
- Taxi fleet is expected to include:
  - Toyota
  - Prius
  - Sienna
  - □ RAV4
  - Nissan NV 200











## Some Lessons Learned and Challenges



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## PILOT VS. DEPLOYMENT

- Ambiguities within the standards
  - Need for "how to use" in many cases!
  - Complexity of deploying the security (1609.2) is significant
  - Protocols & Data elements must be the same for interoperability
  - Three pilots worked together
    - Review of all standards
      - insure same "objects" for the same purpose and meaning
    - Requirements for messages all the same
      - Optional vs. Mandatory
- Product certification (US DOT Requirement) OmniAir and their program
  - Trusted devices - protect the integrity of the trusted environment
  - Fundamentals messages, channel usage, security usage, timing, etc.



Interoperable Incremental Deployment





## **NEED STANDARDS FOR THE APPLICATIONS**

- "Demonstrations" by 6 vendors
  - Fundamental operation ~same
  - BUT Differences
    - Configuration management
    - Operating parameter management
      - "Intensity" of application
  - "Need for ability to test applications
    - Controlled environment
    - Need "testable" requirements for applications Precision!
  - Need more extensive "<u>certification</u>" that applications meet some minimum?









#### CV depends on a "trusted" environment - vehicles & infrastructure

- Message authentication (BSM, SPaT, MAP, TIM, etc....)
- Data encryption of (To preserve privacy)
- Requires Equipment Certification
- Organizational IT security
  - Physical security of the TMC systems
  - Agency login and security practices
- Protection for all connections and data exchanges need to Secure
  - TMC-ATC, ATC-RSU, TMC-RSU - DTLS with X.509 Certificates
- CV Hardware Impact
  - Bardware Security Module (HSM) for the TMC system
  - $\hfill\square$  HSM inside the ASD/OBU and RSU

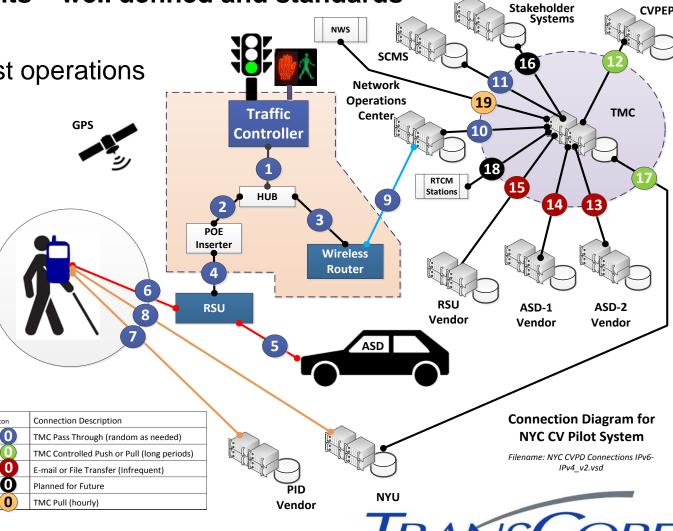




## SECURITY ISSUES – EXTEND EVERYWHERE

#### **Connected Vehicle has security requirements – well defined and standards**

- Issue
  - All of the ITS and IT systems need to adjust operations
  - Classic ITS adopted security measures
  - Certificate management
  - Certificate Revocation Lists
  - Need for real time access to SCMS
  - Secure Boot of all field devices
    - OBU, RSU - Traffic Controller?
  - Physical security re-visited (cabinet keys)
  - Password policies
  - Firewall rules - etc.
  - Misbehavior detection coming soon!





## SCALEABLE AND RELIABLE DEPLOYMENT

- 100 vehicles no problem
- 8,000 revenue generating vehicles
  - Cannot physically access \$\$\$ per minute/hour etc.
  - Project specifications stressed reliability and un-manned recovery
  - Work with the "experts" for installation
- Applications subject to changes
  - Schedule cannot wait until everything is "perfect"
    - 23 weeks to deploy
  - > Needed reliable means to update and add applications
  - > Needed reliable means to "tune" the applications
  - > Likely future changes in communications media and standards





#### CHALLENGE – SCALABLE OTA DATA EXCHANGES

- Push (20 MB+) software updates to 8,000 vehicles efficiently over DSRC
  No WiFi and No LTE/4G
- Developed Scheme to support broadcast updates
  - ASD's read WSA from Control Channel
  - Directed to Service Channel if RSU supports Updates
  - RSU broadcasts available updates
    - Some updates broadcast (continuous) some available by unicast
    - Vehicles initiate update using unicast or monitor broadcast streams
    - Using licensed software to manage the efficient breakdown and assembly
    - Efficient Channel Use
    - Privacy is maintained







## CHALLENGE – LOCATION ACCURACY

#### Location Accuracy –

- Urban Canyons pose issues (both relative V2V and absolute V2I)
  - Dropout at underpasses
  - Loss of GPS lock
- ASD vendor demonstrated RSU triangulation
- Established Compound ASD requirements:
  - Dead reckoning,
  - Triangulation with static DSRC locations,
  - Map matching,
  - Tethered to the vehicle vehicle interface
- Testing is ongoing 10 RSU's worst locations





## **RSU TRIANGULATION**

#### V2X Locate uses

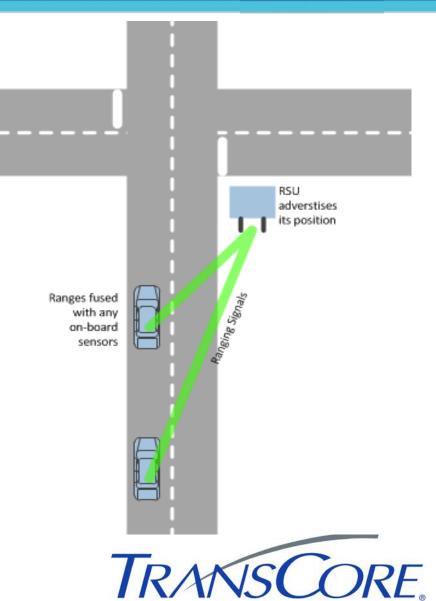
- standard RSUs and OBUs
- standard V2X over the air messages to determine position of vehicle by ranging

# RSU location known \_ Requires High Accuracy! thanks to standard advertisements

Fuses vehicle sensors and GNSS when available.



NYC Connected Vehicle Project For Safer Transportation \* Based on recommended deployment set-up





## **OTHER TECHNICAL CHALLENGES**

- Adjusting the applications for 25 MPH and Freeway speeds
- CAN/J (vehicle) Bus Interface –
  Vendor (OEM) resistance to providing necessary information
  Purchasing a gateway device
- Many different vehicle types and model years
  Varied installation kits
  - $\hfillih$  Fortunately they are fleets we drill holes! and - -
    - Agency can establish terms and conditions of support!







- There is a need for standard [secure] vehicle interface
  - Steering Wheel Angle, Yaw Rates, "hard breaking"
  - Speed, roadway friction, etc.
- Aftermarket devices NEED access to the vehicle data bus
  - Speed, directional, minimum location enhancement
  - Transitional period to embedder safety systems
- Instead OEMs reacting to "security" scares making it harder!
- Future: CV can augment AV
  - Regulations, Intersection operation, Map Dynamics (lane changes, construction, crash/incident/special event mitigation
- NYC vehicle manufacturer cooperation (data interface and design sharing) – non existent!
- 2 Vendors 2 different approaches headache for everyone!





## **DATA RECORDING ISSUES**



#### NYC was not an R&D project!

#### What to collect

- What could I collect?
  - What is the raw data available
- What Do I need?
  - What is the intended use of the data?
- What should I collect?
  - To Justify the costs!



#### What are the costs

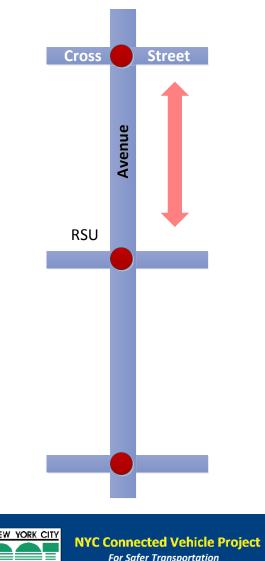
- Backhaul communications
- Storage
- Processing
- FOIA requests
- Subpoena

#### **Privacy Issues**

- Prohibition of keeping PII
- Combination with other sources.
- Data Ownership

#### EXAMPLE – TRAVEL TIME





- Block Spacing ~70M Feet (230')
- 20 MPH 30 feet per second
- DSRC Range ~300M (1000')
- BSMs Xmit @ 10 Hz
- Time between blocks ~8 seconds
- BSMs transmitted 80
- BSMs needed 2 3% a 97% reduction

#### Edge computing @ RSU

- RSU looks for vehicle entry to Intersection
- Transmits one BSM to TMC per vehicle
- TMC matches BSM Vehicle ID
- TMC computes travel time
- Or TMC data times out -



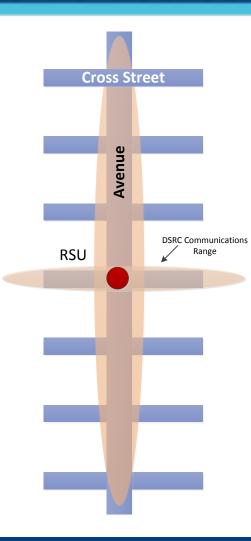
## **OPTIMIZED INTERSECTION CONTROL**

- Edge computing @ traffic controller
  - Queue length Stopped Vehicles
  - vehicle speeds Reported in local BSM
  - Priority and preemption With local communications
  - Incident detection deviation around obstacle
  - Pedestrian presence
- Send to TMC only what needs to be used
  - Platoon management (Freight priority)
  - Alternate route management/diversion
  - Incident detection
  - Travel Times (average link speed)
  - EVP progress (if not provided directly by the vehicle)





## **PRACTICAL DATA COLLECTION - INCIDENTS**



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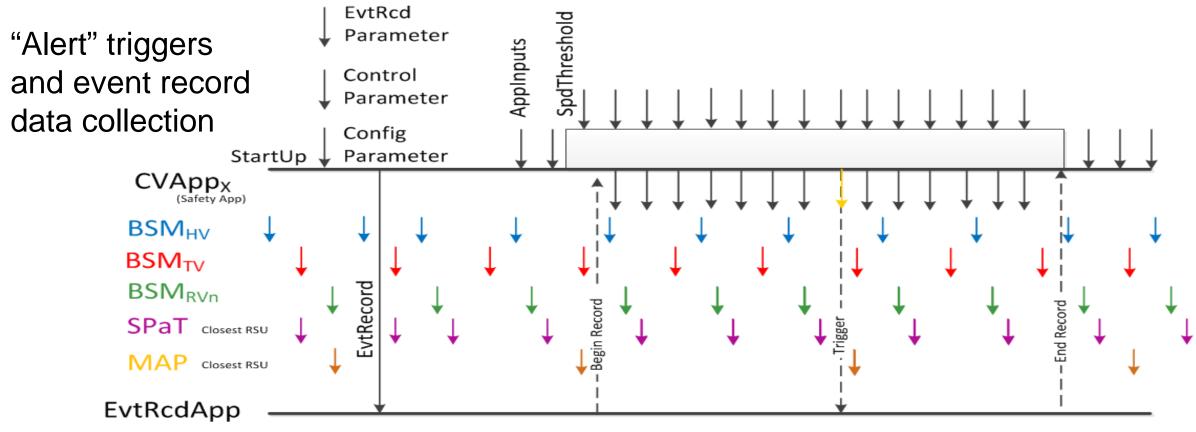
- 1.2 M vehicles in NYC broadcast 83 TB/day
- 13,000 NYC intersections broadcast 3 TB/Day SPaT & Map
- 8,000 vehicles collect 2 TB BSM data/day
- Data *needed* for benefits analysis:
  - How many crashes per day did we prevent
  - How many crashes per day did we mitigate
- Edge computing Onboard Unit (OBU)
  - OBU monitors vehicle operation (S, Yaw, etc.)
  - OBU monitors surrounding vehicles' operation
  - OBU assesses threats
  - OBU alerts driver to mitigate threat
  - OBU records what the caused alert and driver actions





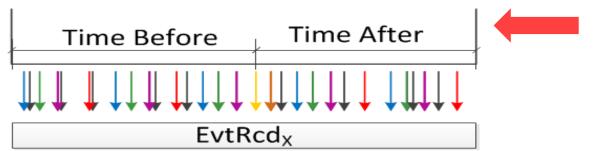
#### SOLUTION "INCIDENT DATA"

#### **INTERMITTENT LOGGING**



- HV Host Vehicle TV – Target Vehicle RV – Remote Vehicle
- n Vehicle 1...n

All of the data collected during  $T_B$ is transferred to the event record, and after the trigger the data is collected and added to the record until  $T_A$  expires.





## **DATA REDUCTION AND PRIVACY PROTECTION**

#### Magnitude of Data

- Instead of 2 TB only 116 GB per day
  - 17 times less and more useful detail (@4 events/hour)
  - Includes SPaT and MAP information
  - @1 event / hour /vehicle = 29 GB/day or 67x reduction!

#### **Privacy Concern**

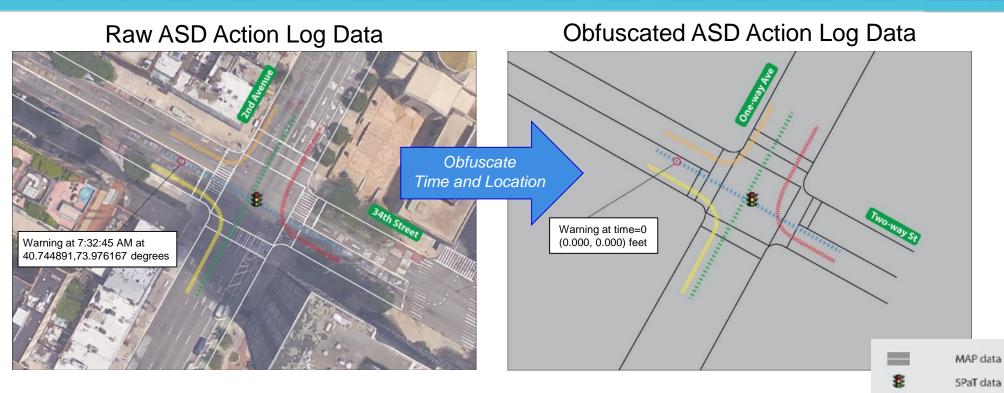
- If BSM data were to be collected -
  - Provides vehicle locations at 0.1 second intervals
  - Time-of-day Stamped to 0.1 second accuracy
  - Police Records indicate "final position" of vehicles and time of day
  - CV data could be used to recreate the accident scene
- Even though CV vehicle ID is randomly changed the raw data can be tracked to an individual vehicle





## **OBFUSCATION OF OBU ACTION LOGS**





- Obfuscation process to scrub precise time and location data
  - Relative details retained
- Non-obfuscated data will be destroyed following the obfuscation process





ITTTT

11111

11111

Event vehicle

Nearby vehicle 1

Nearby vehicle 2 Nearby vehicle 3

Nearby vehicle 4

#### **OTHER EXAMPLES – OPERATIONS DATA**

#### RF Data – Proactive Analysis

- Records first and Last BSM heard from each OBU
- Time-out to find dropouts
- At 1000 ft. vehicle "hears" RSU for 50 seconds
- Actual BSMs from that vehicle 500
- Assuming 4 dropouts actual BSMs needed 8 or 2%
- Edge computing RSU monitor OBU keep first/last
- Same for OBU 98% bandwidth reduction!
- Only 8 BSMs actually captured
- Guess who I saw today
  - Track other OBUs seen throughout the City
  - Approximately 2 bytes per encounter







## **DATA COLLECTION - SUMMARY**

- The CV technology could make "mountains of data" available
  - but there is a cost
  - DSRC Channel time
  - Cellular media monthly limitations
  - Processing and storage
  - Retrieval (FOIA) & Subpoena
- NYC pilot deployment project
  - Tailored data collection to meet needs
  - Concept is to distribute processing to the edge
  - Added RSU locations to collect data











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## **STAY CONNECTED**



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#### Visit CV Pilot and Pilot Site Websites for More Information:

- CV Pilots Program: <u>http://www.its.dot.gov/pilots</u>
- NYCDOT Pilot: <u>https://www.cvp.nyc/</u>
- Tampa (THEA): <u>https://www.tampacvpilot.com/</u>
- Wyoming DOT: <u>https://wydotcvp.wyoroad.info/</u>

