

Why do we need a Dust Detection System

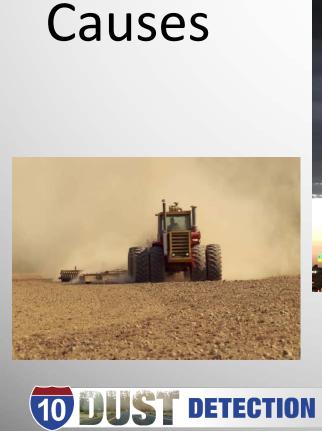
?











Kimley»Horn

ADOT





Dust Related Crashes

- <u>Aug 2010 to Aug 2015</u>
 - **3** Fatal
 - **5** Incapacitating
 - 27 Non-Incapacitating
 - 6 Possible
 - 42 Property Damage Only
- 83 crashes in 5 years

DETECTION







What is a Dust Detection System?

- Radar Detects Approaching Storm
- Sensors Measure Visibility
- Software Determines Appropriate Speed
- Software Sends Messages to VSL and DMS
- CCTV Verifies Conditions
- Pavement Sensors Measure Speed





Challenges: VSLs Unexpected Results







Challenges: VSLs





DETECTION

- White on black versus black on white
- FHWA requested the change
- Had to upload new software update to the sign







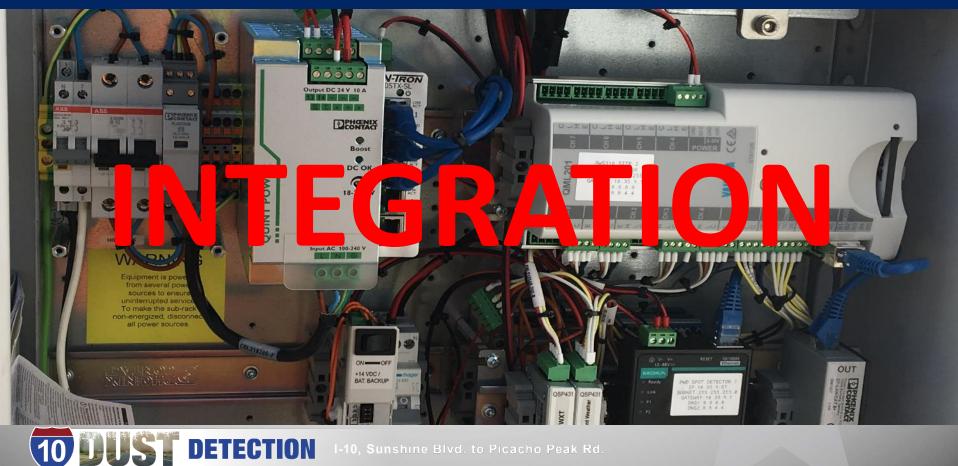
Lessons Learned

- Don't specify equipment that can only be delivered by a single supplier
- ✓ Do consider the final location of the radar during design (we got lucky)
- ✓ Always consider where power and comm is coming from
- ✓ Coordinate early with utilities (not always easy)
- ✓ Allocate adequate budget for new utilities





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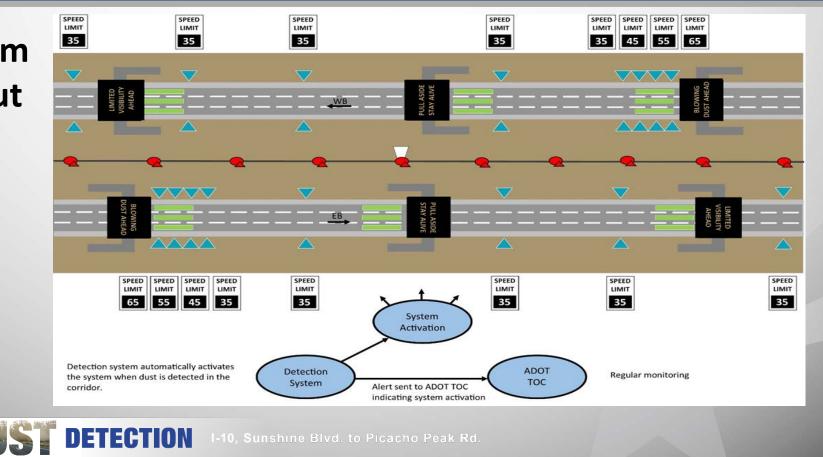


How are we going to make this thing work?





System Layout





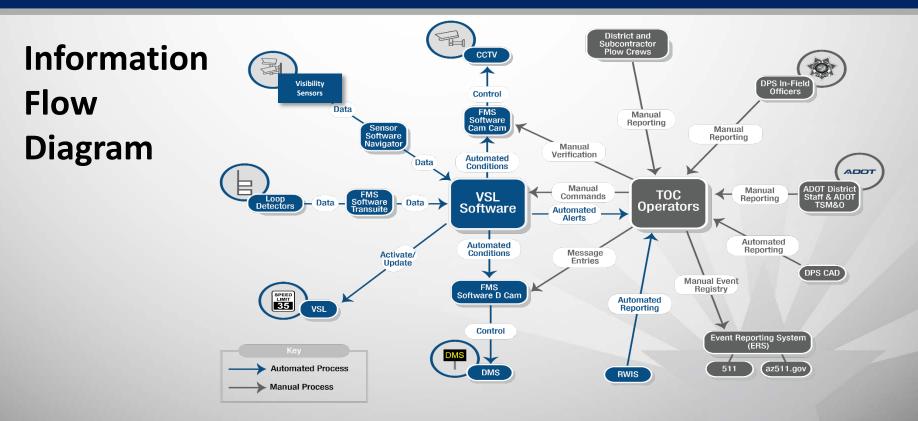


Nobody Touches Nothin'





IST DETECTION





System Activation Thresholds

- Visibility thresholds drive system activation
- Thresholds based on stopping sight distance criteria

<1800' = lower speed limit to 65 <1500' = lower speed limit to 55 <1200' = lower speed limit to 45 <900' = lower speed limit to 35



Dust Variable Speed Limite (VSL) State Diagram

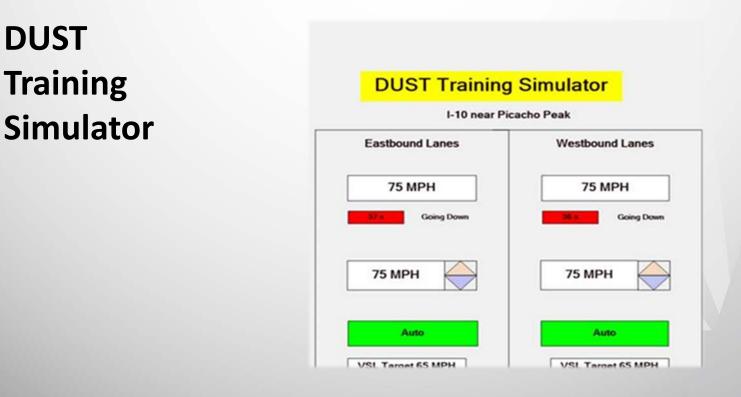
System State CONDITIONS POSSIBLE CAUTION VSL 75 MPH L1 vis< threshold 75 65 OR time_in_state > t_min_ascending AND (vis> storm_spotted_on_radar OR Diagram threshold_65_75) operator_input vis< threshold_ 75_65 OR time_in_state > t_min_ascending AND (vis > on radar OR threshold 65 75) input VSI 1/51 LOW VISIBILITY CONDITIONS CAUTION CONDITIONS 65 MPH 65 MPH CAUTION L2A 12B time_in_state > t_min_descending AND (visthreshold 65 55 OR speed<45) ✓ If "A" happens, then time in state >t min descending AND (vis< time_in_state > t_min_ascending AND vis> threshold_ threshold_65_55 OR 65 65 AND execute "B" speed<45 speed > 45 1/51 EXTREME LOW VISIBILITY CONDITIONS 55 MPH AHFAD 13 time_in_state >t_min_descending AND (vis< threshold 55 45 OR vis> threshold 45 65 AND ✓ Visibility Parameters speed<35) sneed > 35 VSL 45 MPH SLOW DOWN CONDITIONS 14 Configuration Constants ✓ Time Parameters (exact values to be determined _min_ascending 5 min time in state >t min descending AND time in state >t min ascending AND t_min_ascending 5 min (vis< threshold_45_35 OR vis> thres hold_ 35_45 AND threshold 75 65 1800 feet Sneed (25) eneed > 25 threshold 65 55 1500 feet threshold_55_45 1200 feet threshold 45 35 900 feet threshold_35_45 1200 feet threshold_45_55 1500 feet VSL 35 MPH SLOW CONDITIONS threshold_55_65 1800 feet DOWN 15 threshold_55_65 2100 feet threshold_65_75 2400 feet **ST** DETECTION



DUST

Training

UST DETECTION



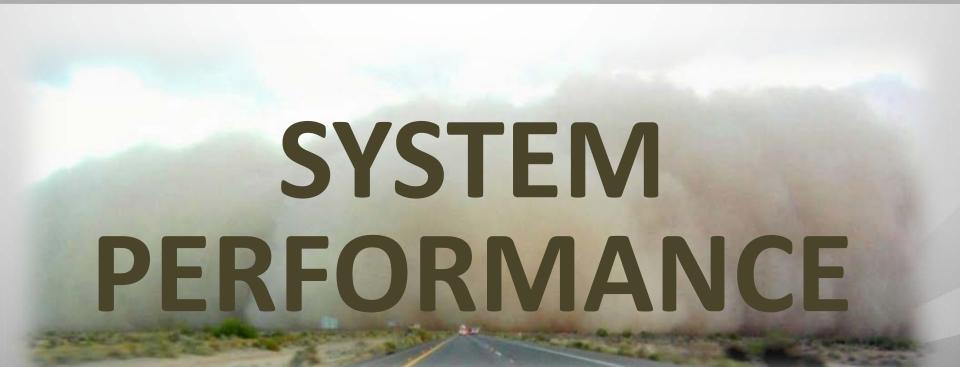


Lessons Learned

- ✓ Budget adequately for integration
- ✓ Start integration sooner
- ✓ Have an offline server to test the system
- ✓ Get basic system operational then add other technologies
- ✓ Include equipment suppliers

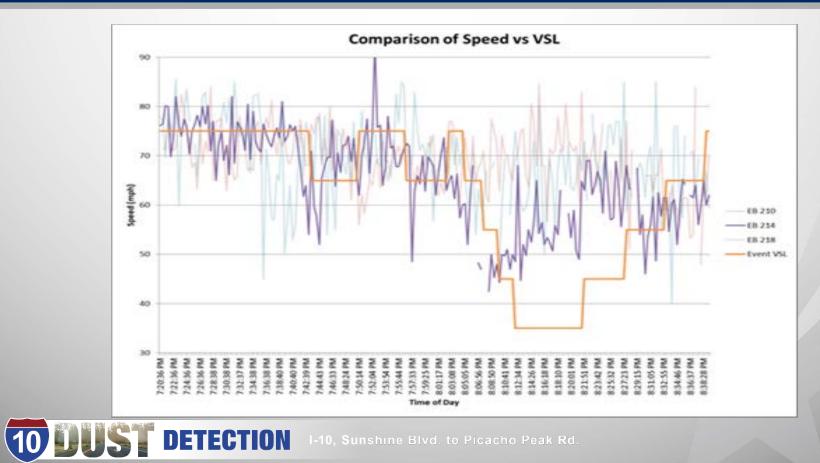
















QUESTIONS

